

A Soft-Real-Time Optimal Scheduler for DAG Tasks with Node-Level Self Dependencies

Shareef Ahmed and James H. Anderson

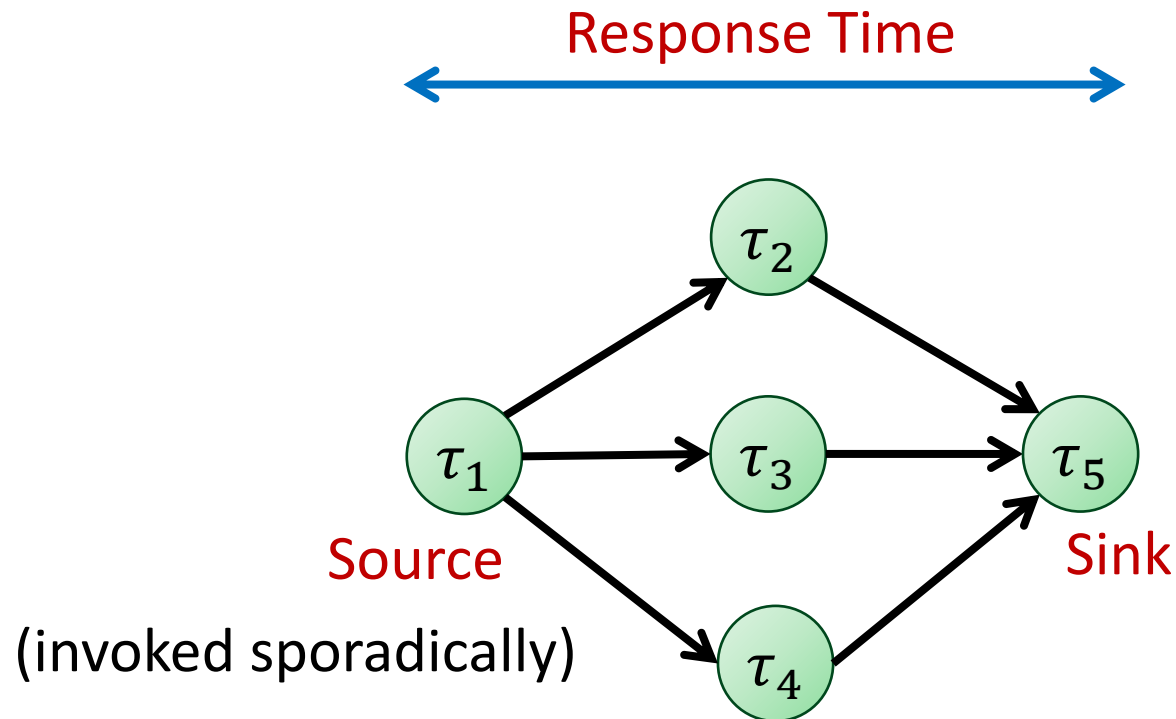


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Processing Graph

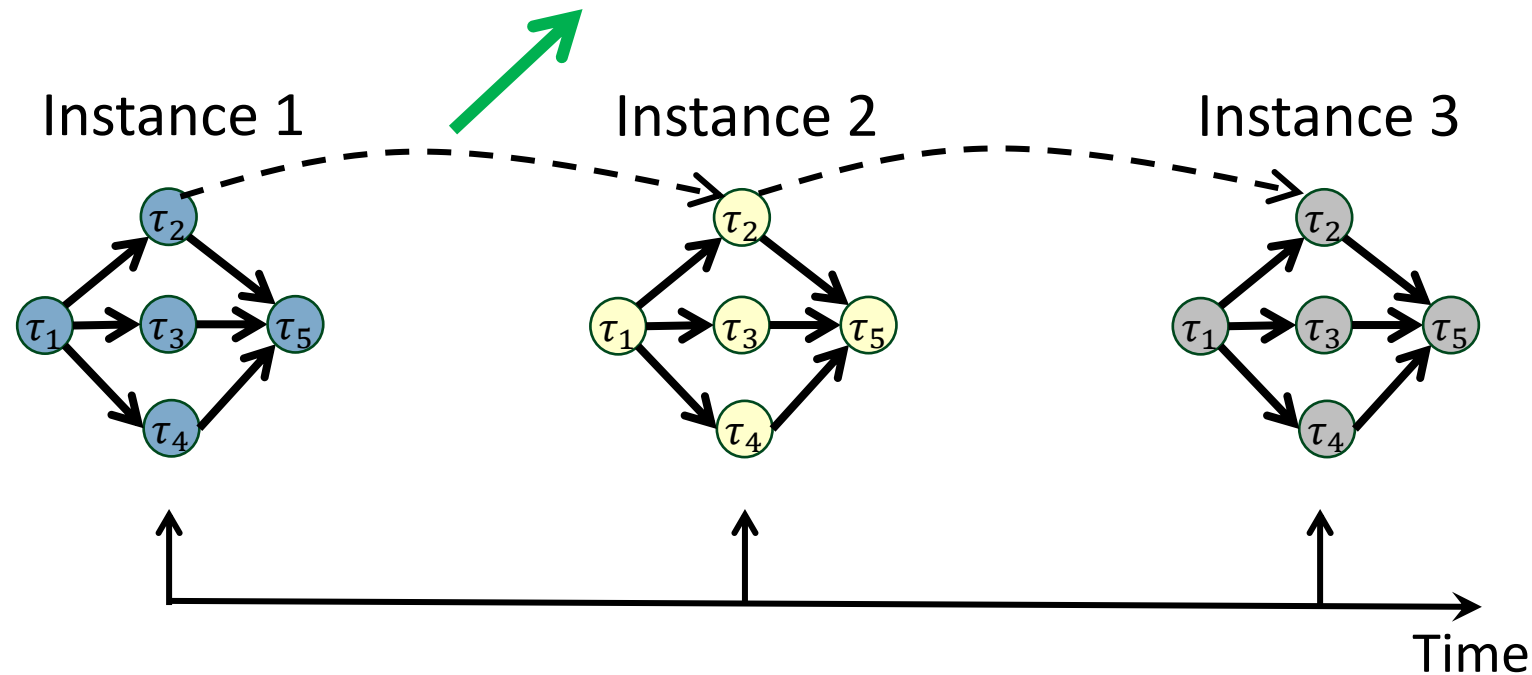


- Node = Task
- Edge = Precedence constraint
- Goal:
 - Bounded response time (SRT)
 - Response time can exceed period

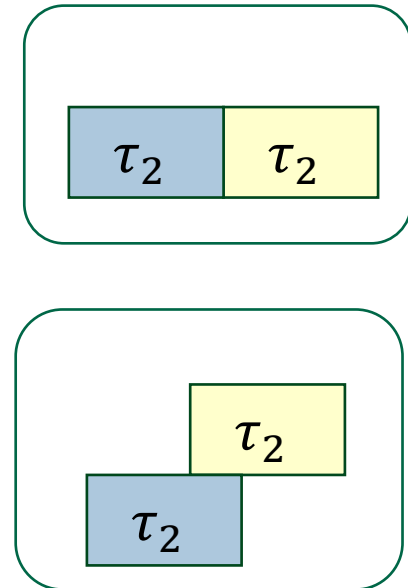


Self-Dependencies Among Node Instances

τ_2 must complete before τ_2 can start execution (Example: Object tracking)

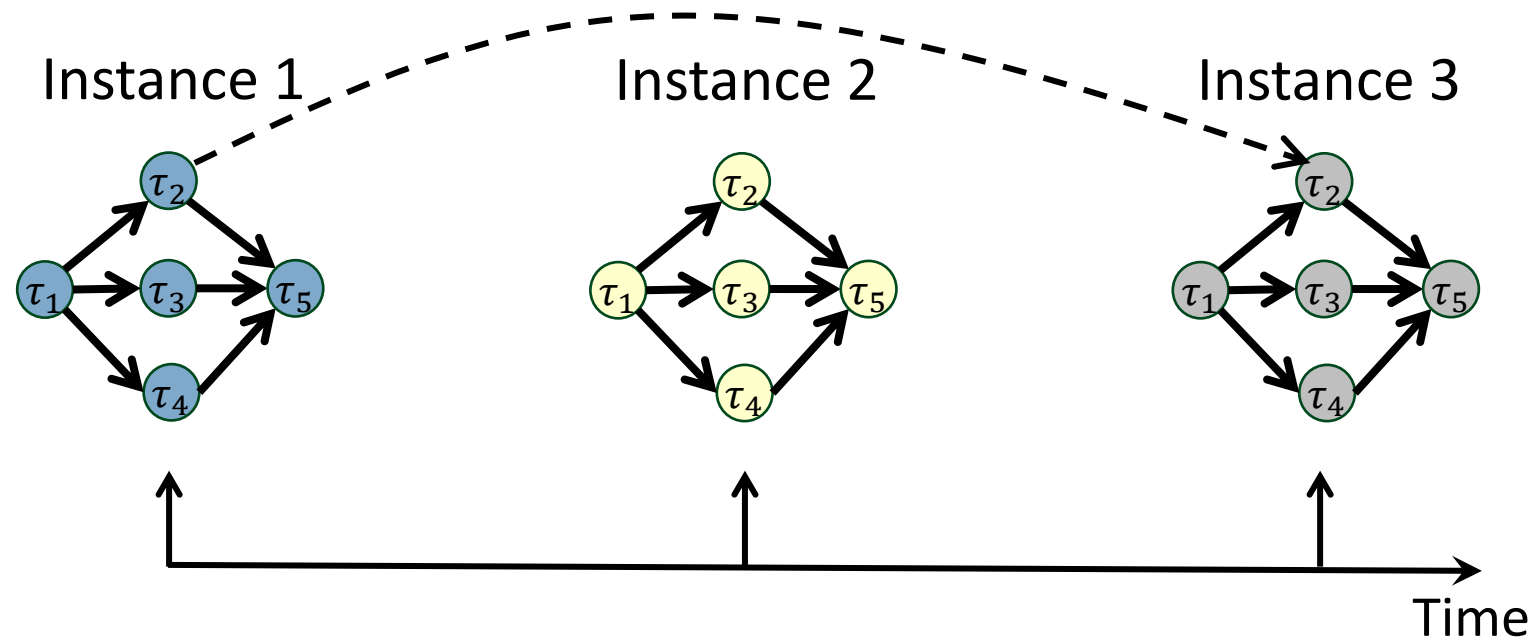


Dependency level = Parallelism level = 1



Self-Dependencies Among Node Instances

Dependency/parallelism level can be arbitrary
[rp-sporadic task model, Amert et al. RTSS 2020]



Dependency level = Parallelism level = 2



Feasibility And Optimality

SRT-Feasible Systems

Total utilization \leq number of processor and Task utilization \leq Dependency level
[Amert et al., RTSS 2020]

SRT-Optimal Scheduler

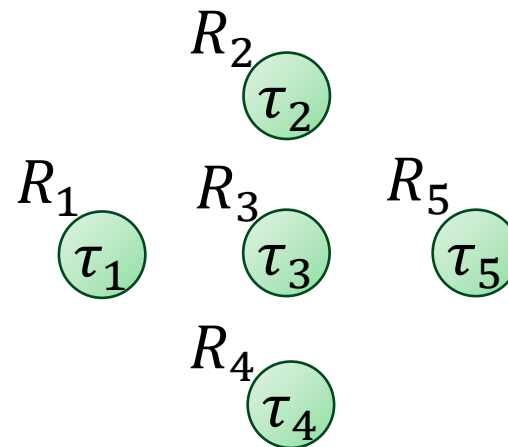
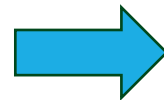
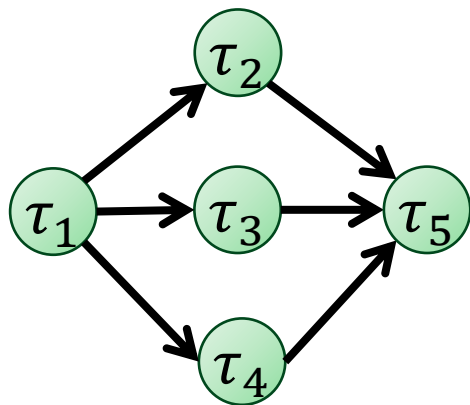
Bounded response time for any SRT-feasible system



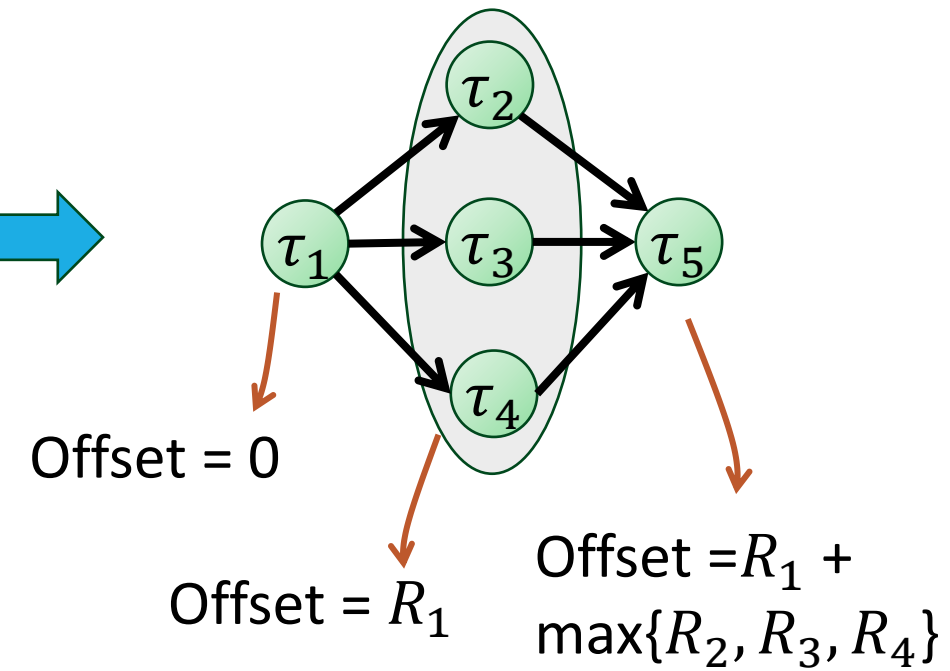
SRT-Optimal Scheduler: Offset-Based Scheduling

SRT-optimal but R_i values can be pessimistically large

R_i = Response-time bound
(assuming independent tasks)



$$R_1 + \max\{R_2, R_3, R_4\} + R_5$$



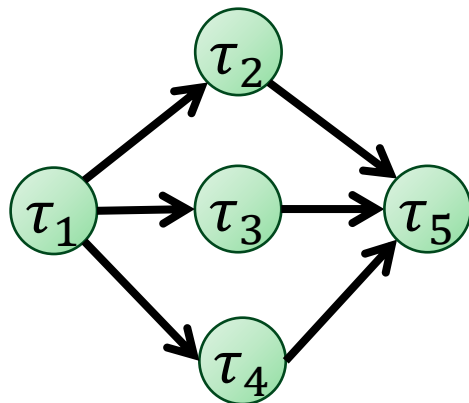
- Liu and Anderson, RTSS 2010
- Yang and Anderson, RTNS 2016
- Amert et al., RTSS 2020



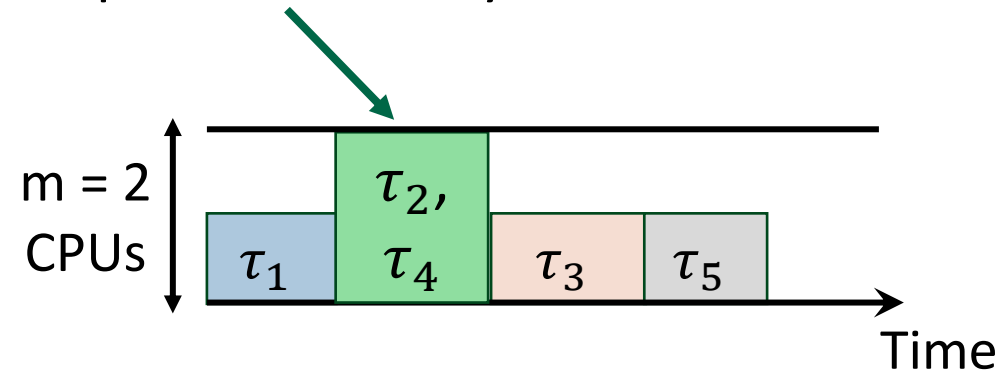
Non-Decomposition-Based Analysis

Applicable for HRT DAG tasks

- Graham, Siam J. of Appl. Math., 1969
- Melani et al., ECRTS 2015
- He et al., RTSS 2022
- Fonseca et al., RTJ 2019

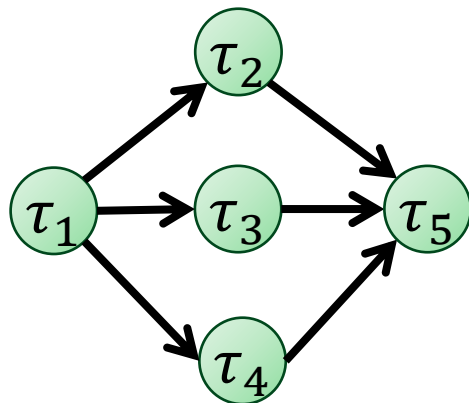


All processors busy

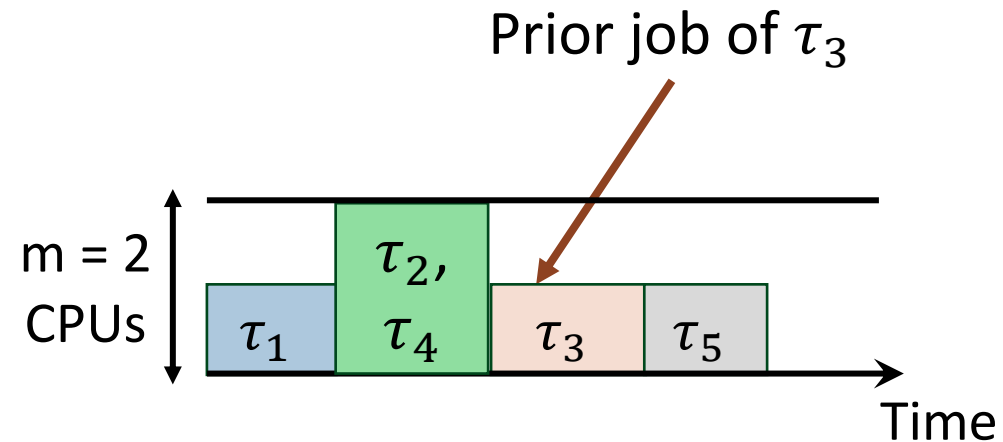


Non-Decomposition-Based Analysis

Applicable for HRT DAG tasks



- Graham, Siam J. of Appl. Math., 1969
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- Is there an **SRT-optimal scheduler** for a DAG task with self-dependencies that can be **analyzed without decomposition**?

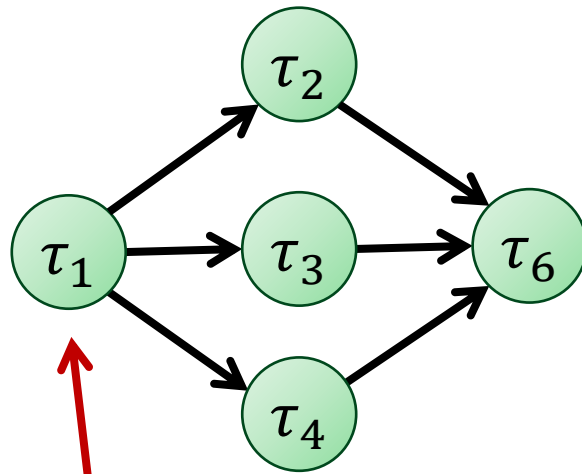
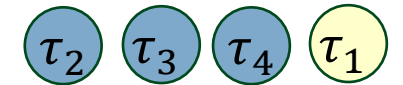


Challenge: Priority Assignment

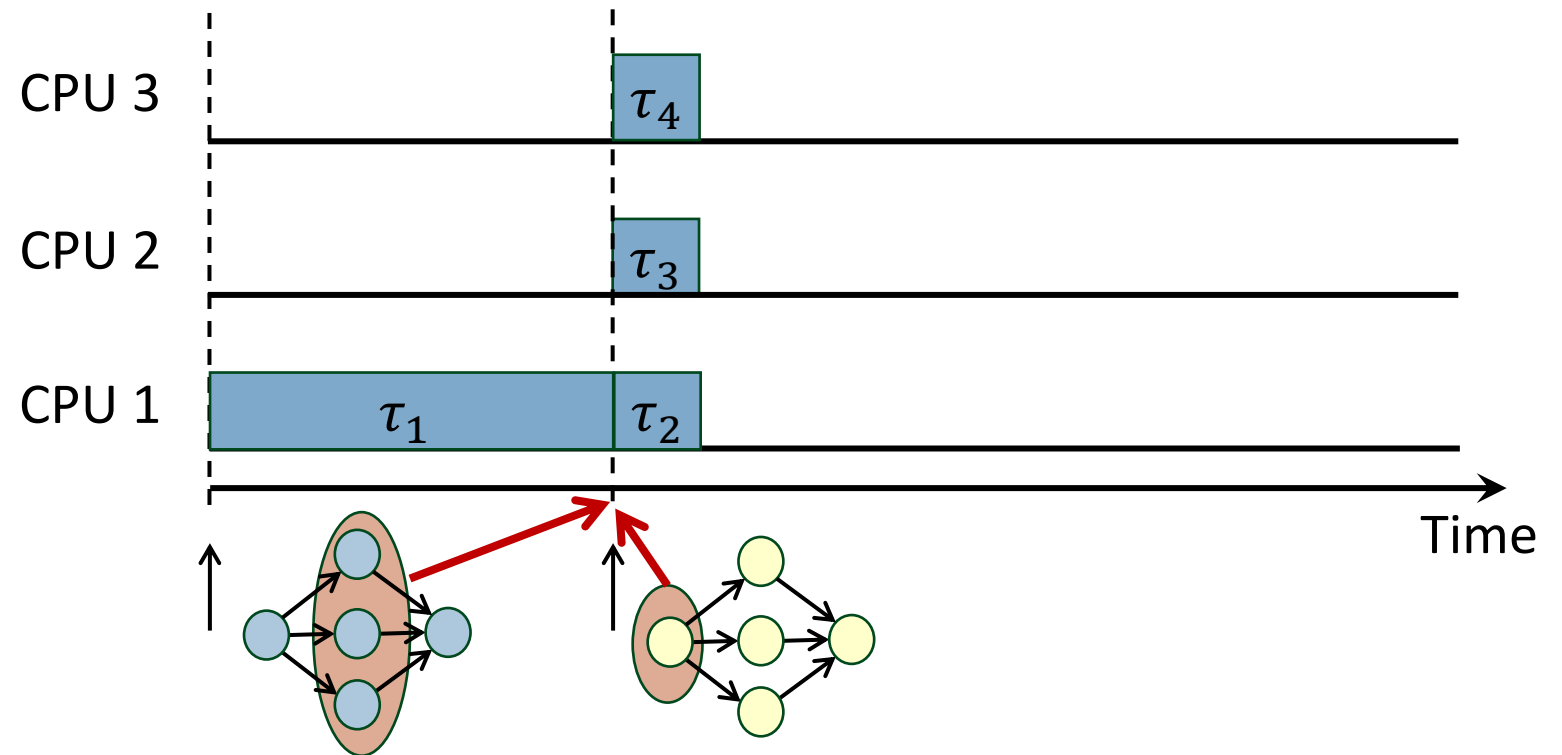
How to set cross-instance job priorities?

GEDF/FIFO: prioritize jobs of earlier instances

High priority → Low priority



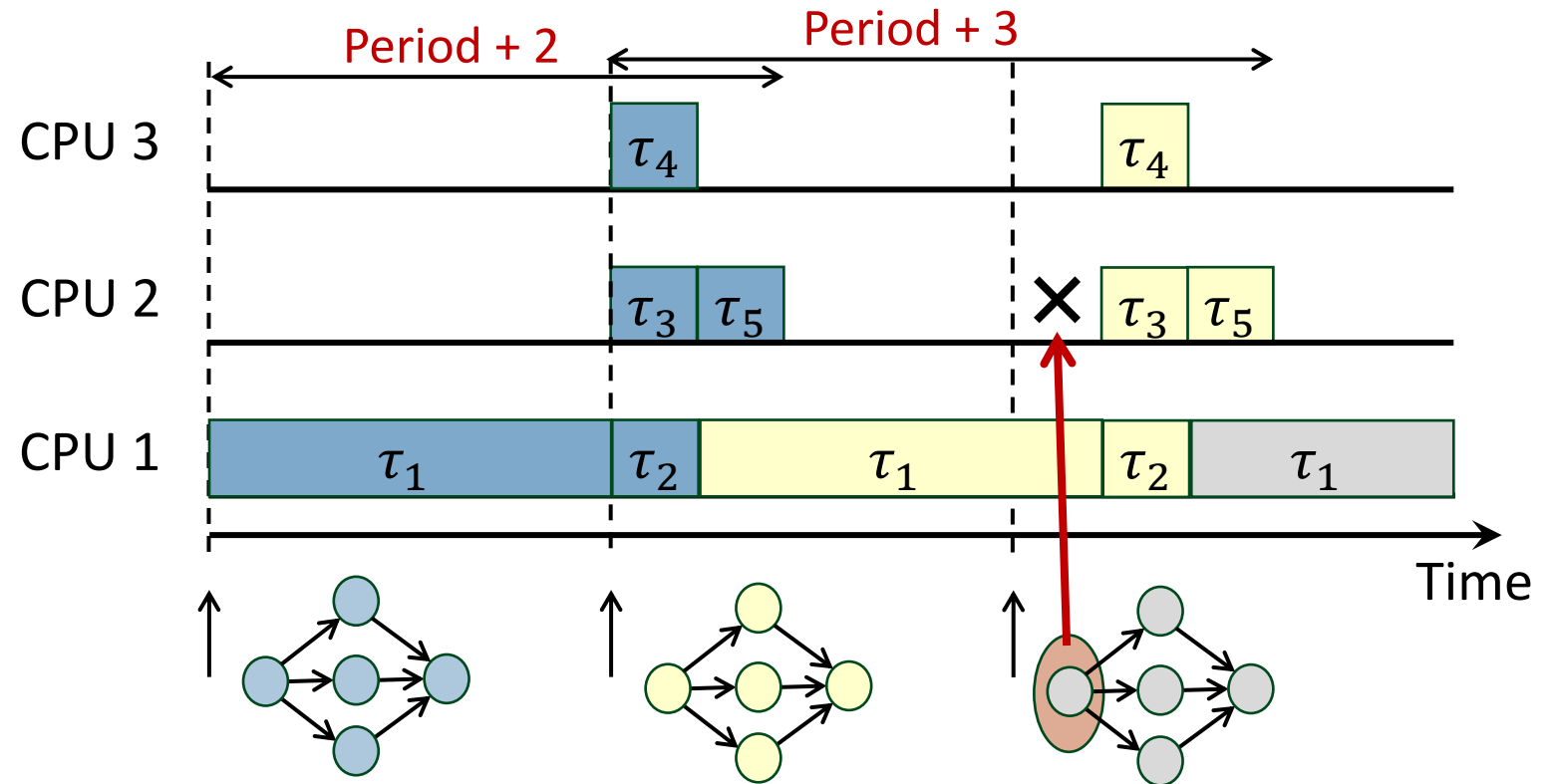
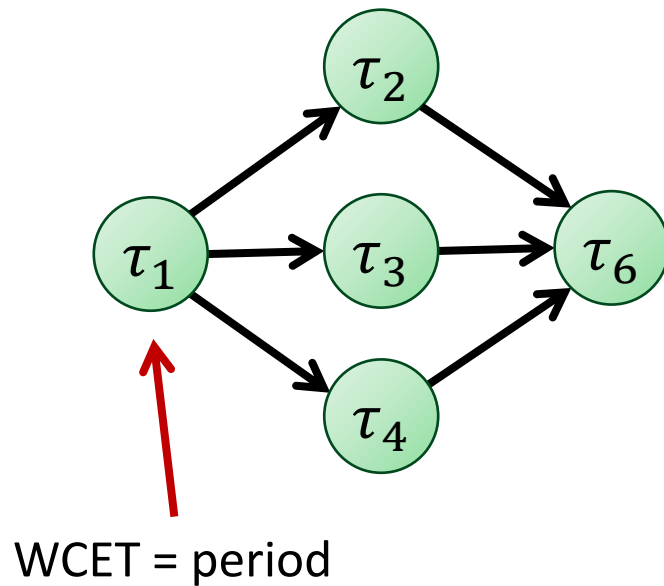
WCET = period



Challenge: Priority Assignment

How to set cross-instance job priorities?

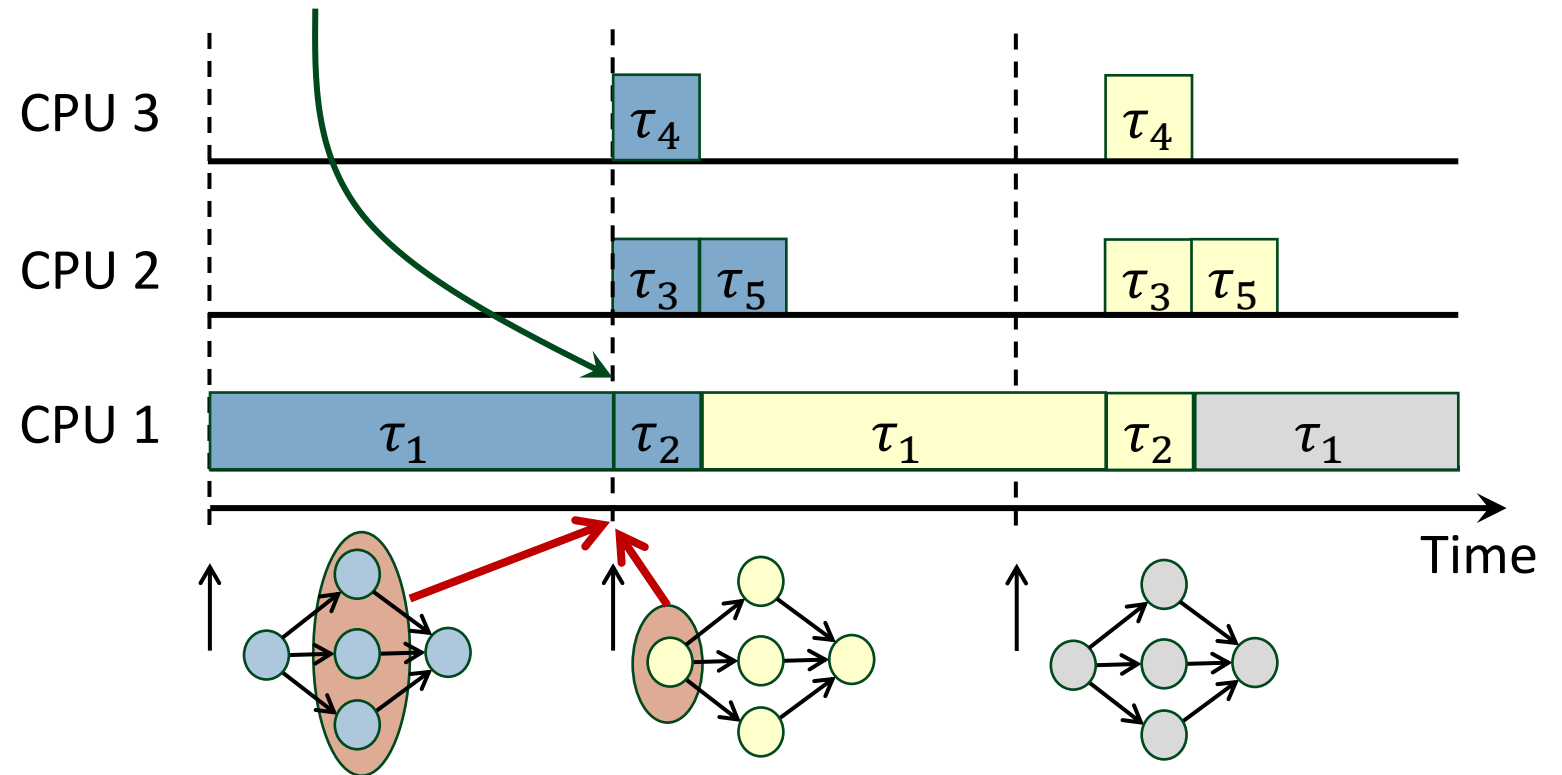
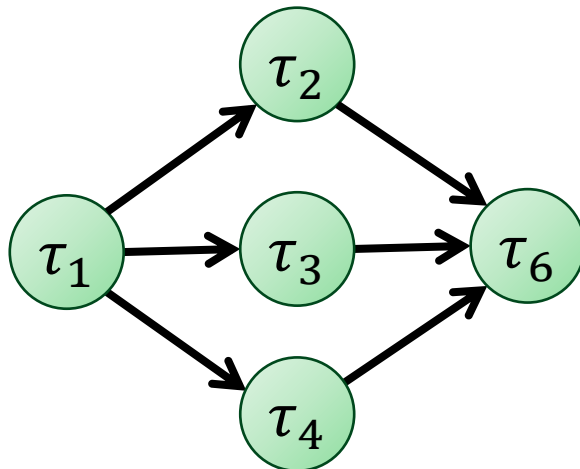
GEDF/FIFO: prioritize jobs of earlier instances



Priority Assignment

Goal: Ensure concurrent progress of multiple DAG instances

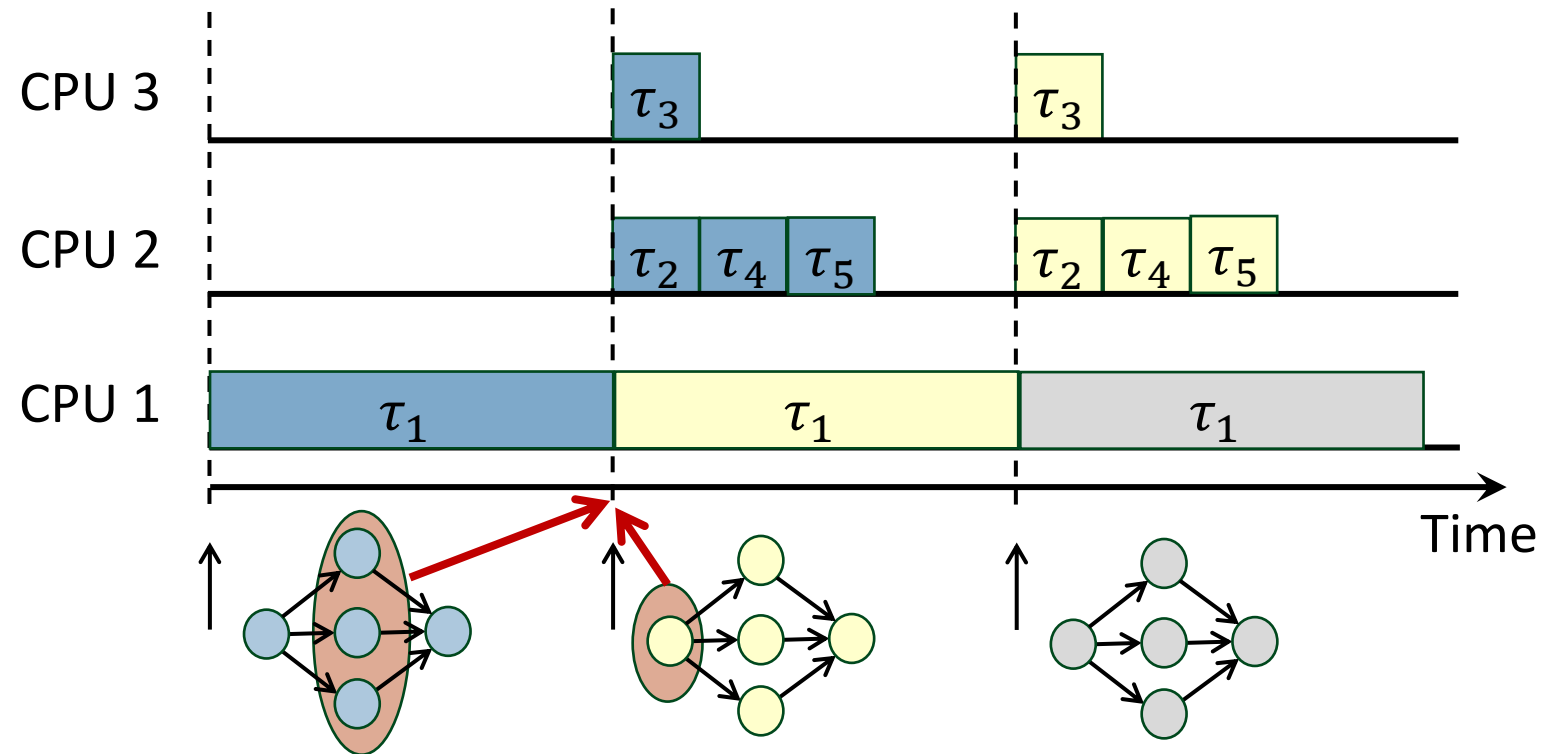
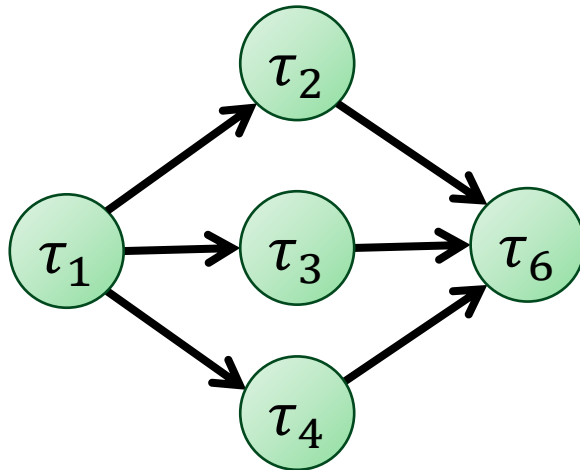
Give τ_1 high-enough priority to be scheduled



Priority Assignment

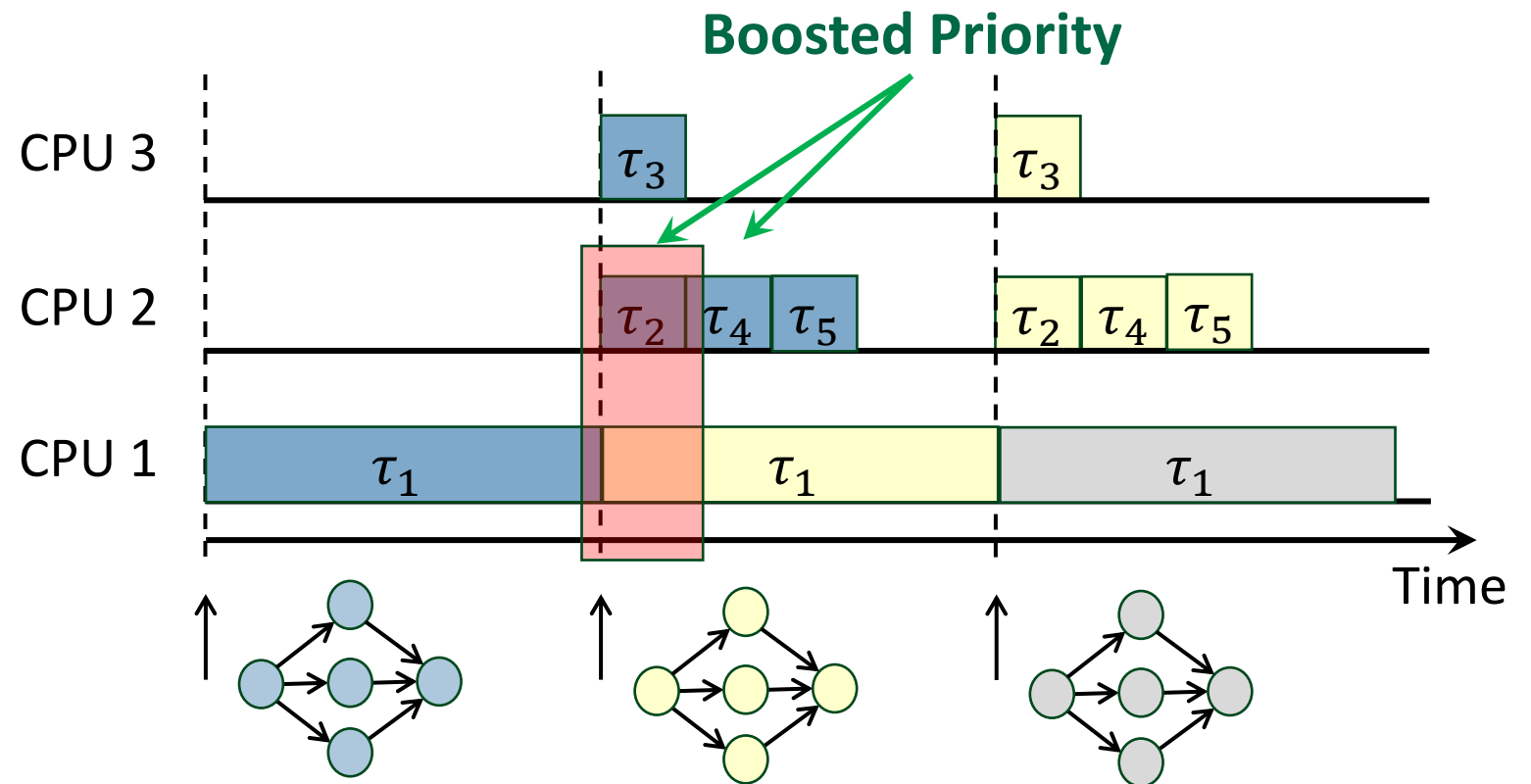
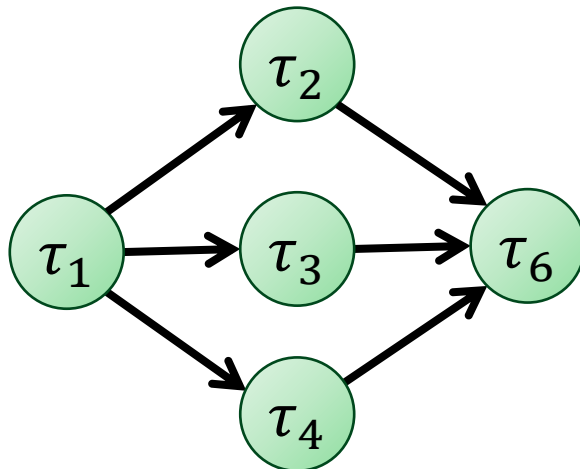
Goal: Ensure concurrent progress of multiple DAG instances

Give τ_1 high-enough priority to be scheduled



Priority Assignment

- Prioritize jobs of earlier instances
- But, **the lowest-indexed pending job** of each DAG instance is **priority-boosted**

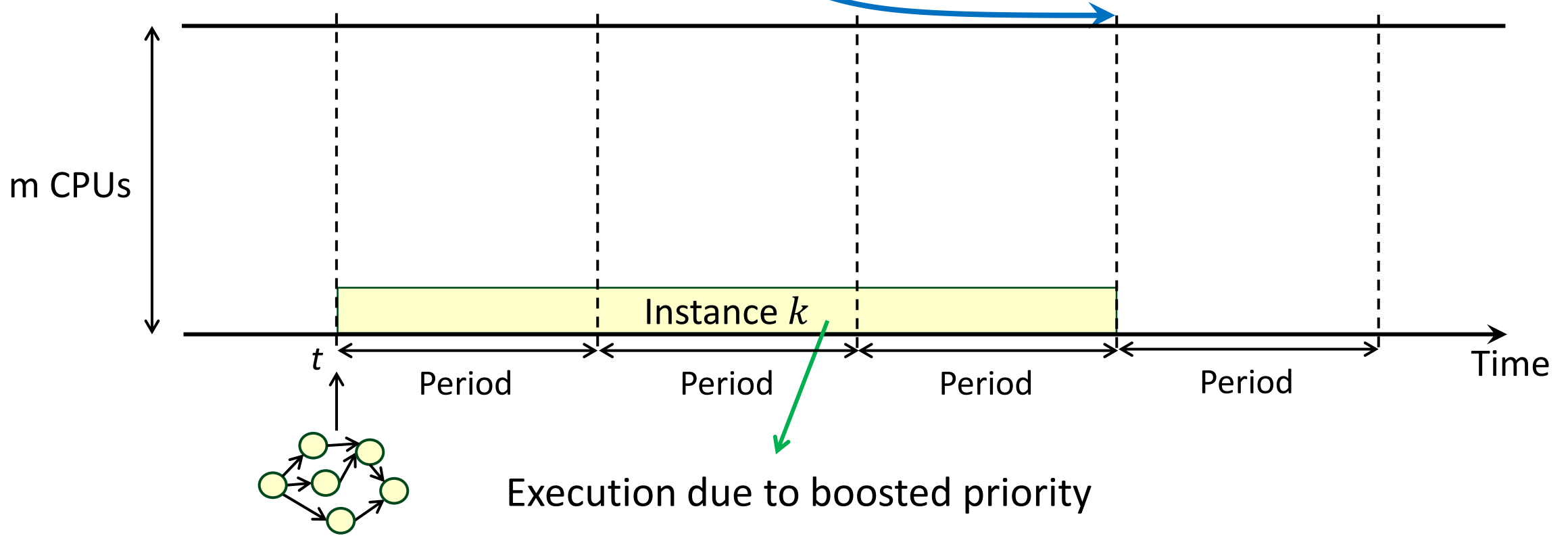


Response-Time Analysis

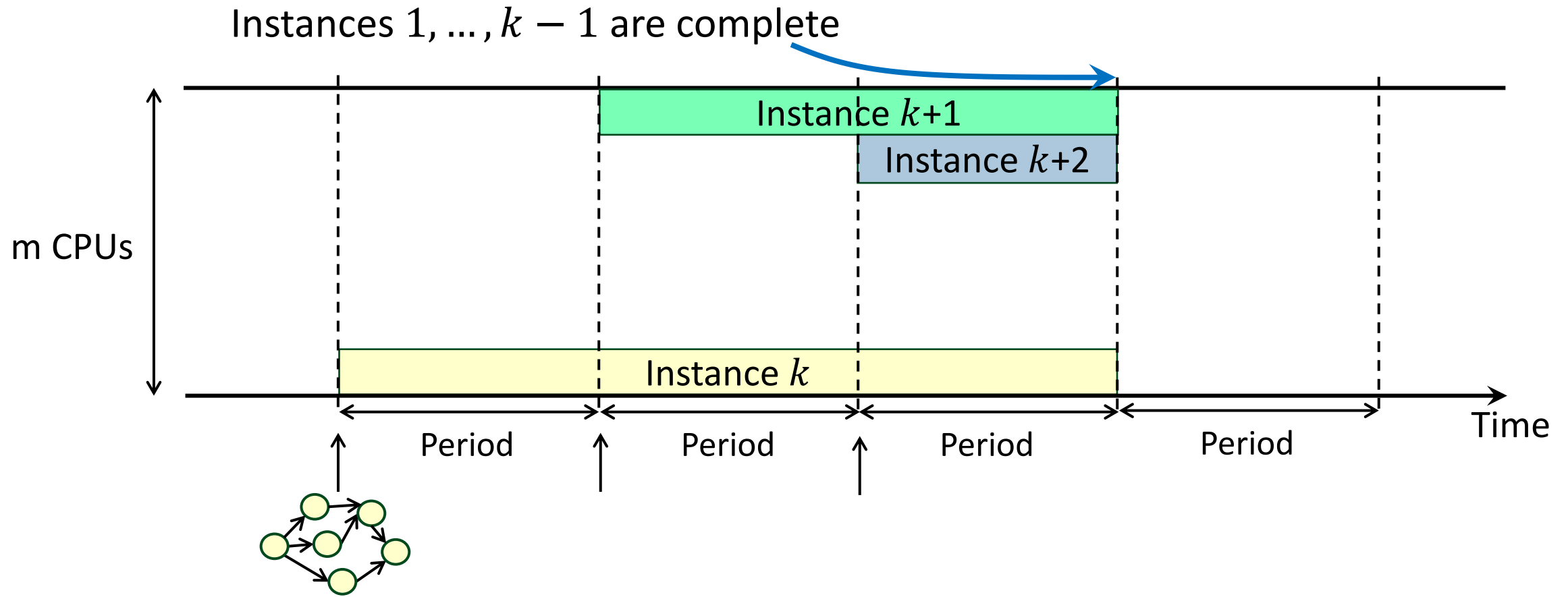
How can a DAG's response time be at most $x \cdot \text{Period}$?

Instances 1, ..., $k - 1$ are complete

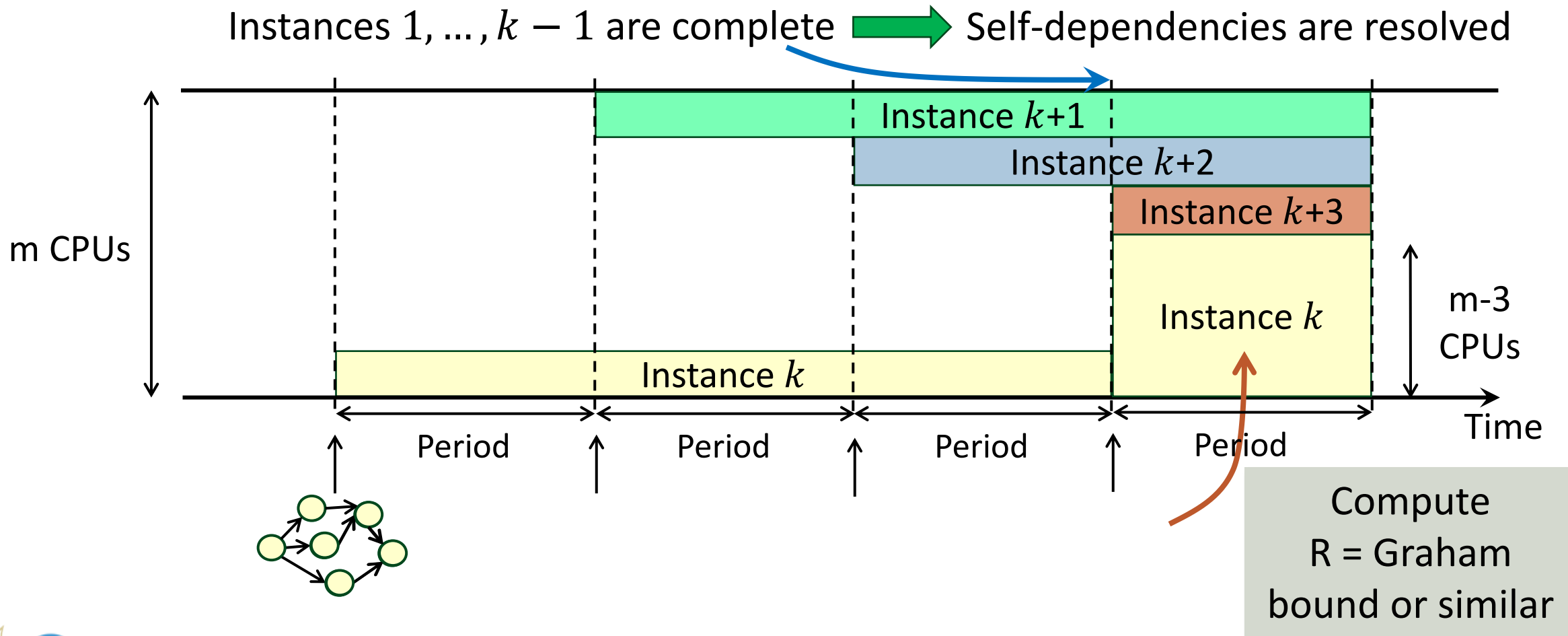
Consider $x = 4$



Response-Time Analysis

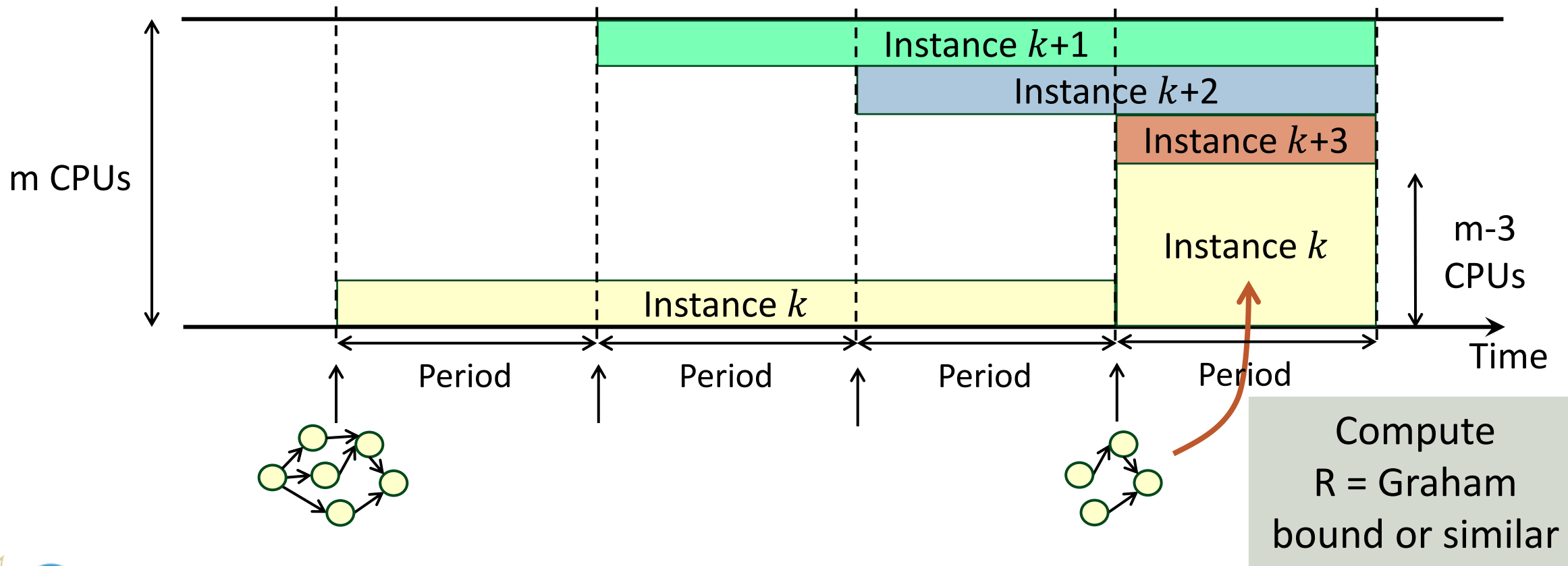


Response-Time Analysis



Response-Time Analysis

$$R \leq \text{Period} \Rightarrow \text{Response time} \leq x \cdot \text{Period}$$



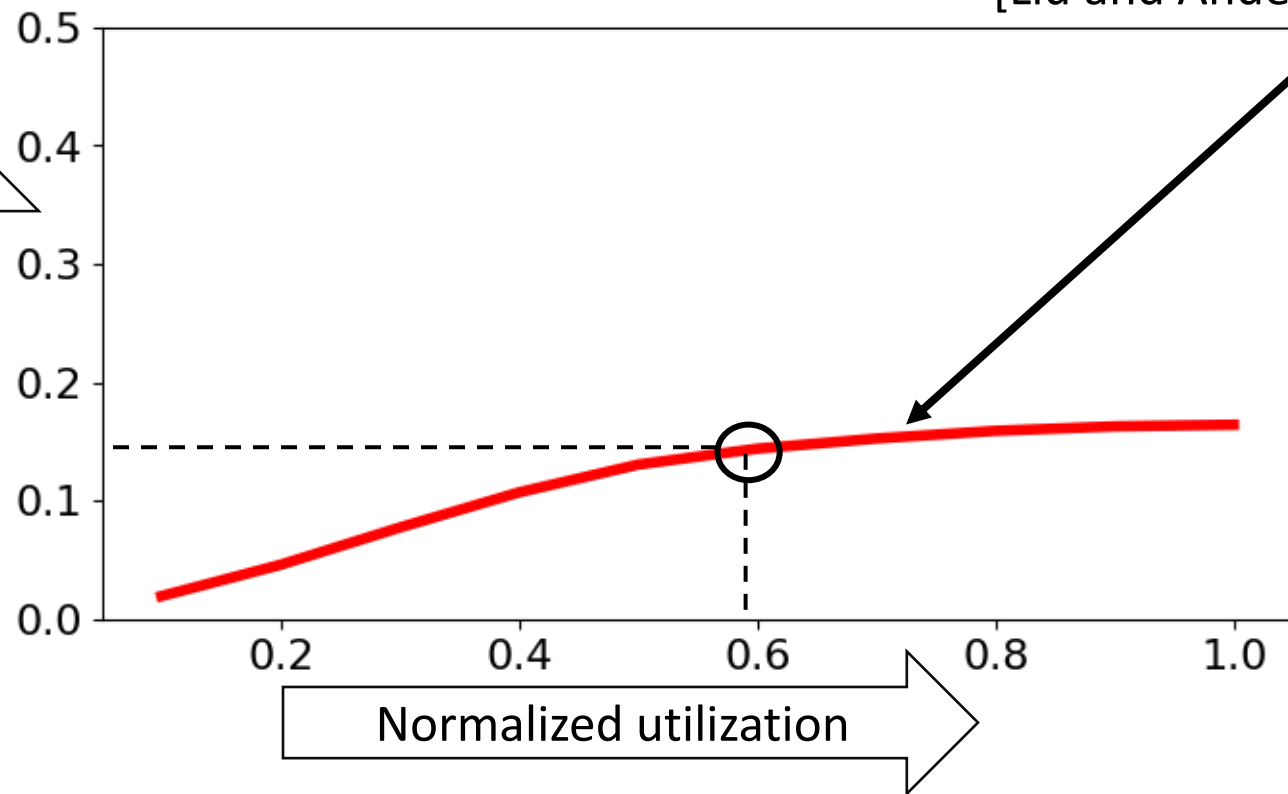
Evaluation

Dependency level = 1

Bound under **our scheduler**

Bound under **offset-based scheduler**

[Liu and Anderson, RTSS 2010]

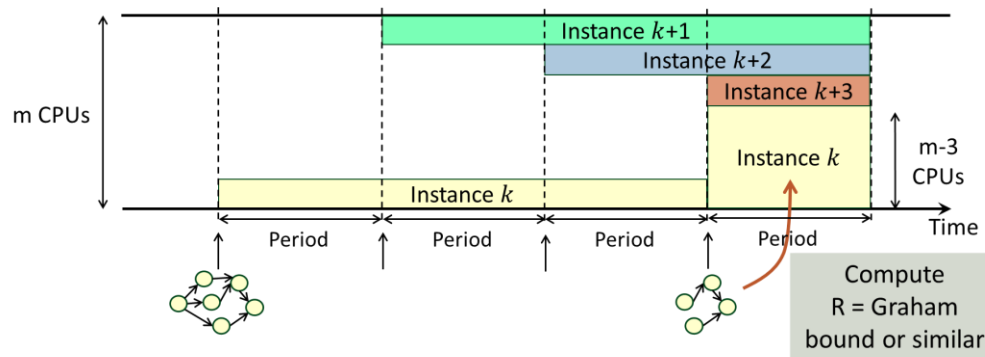
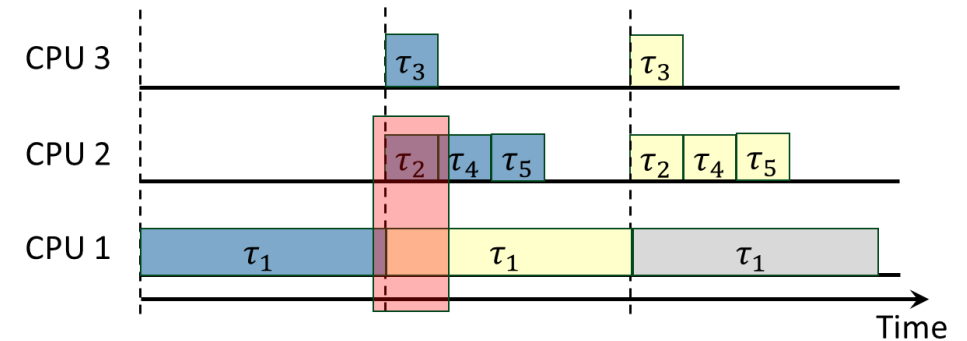
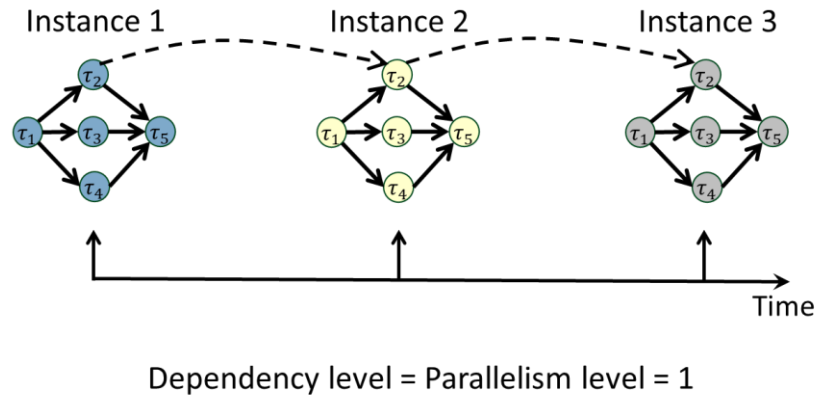


≤ 1 means
lower bound

No dominance!



Conclusion & Thank You!



Future work

- Multi-DAG system
- Non-preemptive systems

